

52. (Original) The article of claim 37, wherein said assessment is selected from a group consisting of: real-time and delayed.
53. (Original) The article of claim 42, wherein said assessment is selected from a group consisting of: real-time local, real-time remote, manual, and embedded.
54. (New) A method for controlling a robotic apparatus comprising:
- (a) reading sensor data in communication with said apparatus;
 - (b) processing sensor data;
 - (c) transmitting said sensor data to a receiver in communication with said apparatus;
 - (d) parsing said sensor data;
 - (e) activating an actuator of said robot in response to said parsed data;
 - (f) interacting with said apparatus in a dynamic feedback control system,
 - (g) wherein the step of processing said sensor data includes functions selected from the group consisting of: analog to digital converting, compressing said data, mapping said data, thresholding said data, and pattern recognition.

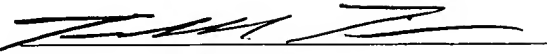
REMARKS

In view of the forgoing remarks associated with the attached Information Disclosure Statement, it is submitted that all of the claims remaining in the application are now in condition for allowance and such action is respectfully requested. Should any questions arise in connection with this application or should the Examiner believe that a telephone conference with the undersigned would be helpful in resolving any remaining issues pertaining to this application, the undersigned respectfully requests that she be contacted at the number indicated below.

For the reasons outlined above, an allowance of this application are respectfully

requested.

Respectfully submitted,

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